

GOVT. DEGREE COLLEGE FOR MEN, SRIKAKULAM

DEPARTMENT OF MATHEMATICS

STUDENT SEMINARS

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S.No.	Name of the Student	Hallticket No.	Group	Topic	Signature
1	T. Madavi	1900140052	MECS	Basic Extension Theorem	T. Madavi
2	P. Leelavathi	1900140032	MECS	1.S.T (1,2,1), (2,1,1) & (1,1,2) form a basis for $\mathbb{R}^3(\mathbb{R})$ 2.Determine $\left\{ \begin{bmatrix} a & b & c \\ b+c & 0 & a+b \end{bmatrix}, a, b \in \mathbb{R} \right\}$ is a subspace of $\mathbb{R}_{2 \times 3}$	D Leelavathi
3	L. Sai Durga Prasad	1900142030	MPCS	Find the Transformation Matrix from the basis (e_1, e_2, e_3) to the Basis (1,2,0), (2,-1,3) & (1,1,1)	Lolla Sai Durga Prasad.
4	P. Anitha	1900142041	MPCS	If W_1 & W_2 are subspaces of a finite dimensional vector space $V(f)$ then $\dim(W_1 + W_2) = \dim(W_1) + \dim(W_2) - \dim(W_1 \cap W_2)$	P. Anitha
5	S. Koteswara Rao	19001410044	MPC	Find the characteristic roots & the corresponding characteristic vectors of the Matrix $A = \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix}$	Seepana. koteswara Rao
6	L. Ramya	1900142029	MPCS	State and Prove Cayley-Hamilton Theorem	Laddi. Ramya
7	L. Krishna Rao	1900140024	MECS	Explain Cauchy-Schwarz & Bessel's Inequality	Lkr
8	A. Hitesh Reddy	1900140005	MECS	Linear Sum & Sub Space	A. Hitesh Reddy
9	P. Rakesh	1900140032	MECS	Verify C-H Theorem for the Matrix $A = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & -1 & 1 \end{bmatrix}$	Pudi. Rakesh
10	P. Anil Kumar	1900140043	MECS	State and Prove Stoke's Theorem	P. Anil Kumar
11	T. Mohini Kumar	1900142054	MPCS	State & Prove Green's Theorem	T. Mohini Kumar
12	K. Ananth Rao	1900143020	MPE	State & Prove Gauss Divergence Theorem	K. Ananth Rao

21) 2.3.3

Show that $(1, 2, 1), (2, 1, 1)$ and $(1, 1, 2)$ form a basis for \mathbb{R}^3 (\mathbb{R})

Space for solution:

$$\text{let } a(1, 2, 1) + b(2, 1, 1) + c(1, 1, 2) = 0 \text{ for } a, b, c \in \mathbb{R}$$

$$(a, 2a, a) + (2b, b, b) + (c, c, 2c) = 0$$

$$\Rightarrow (a+2b+c, 2a+b+c, a+b+2c) = 0, (0, 0, 0)$$

$$a+2b+c = 0, 2a+b+c = 0, a+b+2c = 0$$

$$\begin{vmatrix} 1 & 2 & 1 \\ 2 & 1 & 1 \\ 1 & 1 & 2 \end{vmatrix} \begin{vmatrix} a \\ b \\ c \end{vmatrix} = \begin{vmatrix} 0 \\ 0 \\ 0 \end{vmatrix}$$

$$\begin{aligned} n &= (n_1, n_2, n_3) = a(1, 2, 1) \\ &\quad + b(2, 1, 1) + \\ &\quad = (a+2b+c, 2a+b+c, a+b+2c) \end{aligned}$$

$$\Rightarrow 1(2-1) - 2(4-1) + 1(2-1) = 1-6+1 = -4 \neq 0$$

$\therefore a = b = c = 0$ the given set is linearly independent

The augmented matrix (1)

$$\left| \begin{array}{ccc|c} 1 & 2 & 1 & n_1 \\ 2 & 1 & 1 & n_2 \\ 1 & 1 & 2 & n_3 \end{array} \right| \xrightarrow{\begin{array}{l} R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - R_1 \end{array}} \left| \begin{array}{ccc|c} 1 & 2 & 1 & n_1 \\ 1 & -3 & -1 & n_2 - 2n_1 \\ 0 & -1 & 1 & n_3 - n_1 \end{array} \right| \xrightarrow{R_3 \rightarrow R_3 - R_2} \left| \begin{array}{ccc|c} 1 & 2 & 1 & n_1 \\ 0 & -3 & -1 & n_2 - 2n_1 \\ 0 & 0 & 4 & n_3 - n_2 + 3n_1 \end{array} \right|$$

$$\begin{aligned} a+2b+c &= n_1 \\ -3b-c &= n_2 - 2n_1 \\ 4c &= -n_1 - n_2 + 3n_1 \\ c &= -\frac{n_1 - n_2 + 3n_3}{4} \end{aligned}$$

$$\begin{aligned} -3b &= n_2 - 2n_1 + c \\ &= n_2 - 2n_1 + (-n_1 - n_2 + 3n_3) \\ &= 4n_2 - 8n_1 - n_1 - n_2 + 3n_3 \\ &= -9n_1 + 3n_2 + 3n_3 \end{aligned}$$

$$b = \frac{-3n_1 - n_2 - n_3}{4}$$

$$\therefore n = \frac{9n_1 - 3n_2 + n_3}{4} (1, 2, 1) + \frac{3n_1 - n_2 - n_3}{4} (2, 1, 1) + \frac{(-n_1, n_2 + 3n_3)}{4} (1, 1, 2)$$

$$\begin{aligned} a+2b+c &= n_1 \\ a &= n_1 - 2b + c \\ &= n_1 + 2(-\frac{9n_1 - 3n_2 + n_3}{4}) \\ &= \frac{n_1 - 9n_2 - 3n_3}{4} \\ &+ \frac{n_1 - 9n_2 - 3n_3}{4} \\ &= \frac{9n_1 - 3n_2 + n_3}{4} \end{aligned}$$

The given set is linearly independent and spans \mathbb{R}^3 and hence is a basis of \mathbb{R}^3

Signature: P. Lakshmi

12) 3.3.1

find the transformation matrix from the basis $\{e_1, e_2, e_3\}$
to the basis $\{(1, 2, 0), (2, -1, 3), (1, 1, 1)\}$.

Space for solution:

In $V_3(\mathbb{R})$,

$$e_1 = (1, 0, 0), e_2 = (0, 1, 0), e_3 = (0, 0, 1)$$

let us express the elements of basis on linear combination
of e_1, e_2, e_3 ,

$$\begin{aligned}(1, 2, 0) &= a(1, 0, 0) + b(0, 1, 0) + c(0, 0, 1) \\ &= (a, 0, 0) + (0, b, 0) + (0, 0, c) \\ &= (a, b, c)\end{aligned}$$

$$\Rightarrow a=1, b=2, c=0 \quad (\text{equating the corresponding coordinates})$$

$$\therefore (1, 2, 0) = 1(1, 0, 0) + 2(0, 1, 0) + 0(0, 0, 1)$$

similarly $(2, -1, 3) = 2(1, 0, 0) + (-1)(0, 1, 0) + 3(0, 0, 1)$

$$(1, 1, 1) = 1(1, 0, 0) + 1(0, 1, 0) + 1(0, 0, 1)$$

The transformation matrix

$$P = \begin{bmatrix} 1 & 2 & 1 \\ 2 & -1 & 1 \\ 0 & 3 & 1 \end{bmatrix}$$

13) 3.3.2

(a) determine $\left\{ \begin{bmatrix} a & b & c \\ b+c & 0 & ab \end{bmatrix}; a, b \in \mathbb{R} \right\}$ is a subspace of $\mathbb{R}_{2 \times 3}$

(b) determine if $\{\omega_1 = (1, -1, 0), \omega_2 = (0, 2, 1), \omega_3 = (2, 4, 3)\}$ is a subspace of \mathbb{R}^3

(b) Space for solution:

First let us verify the closure axiom of adding

$$(1, -1, 0) + (0, 2, 1) = (1, 1, 1) \notin \omega$$

$$(0, 2, 1) + (2, 4, 3) = (2, 6, 4) \notin \omega$$

Hence '+' is not closed in ' ω ' Hence ' ω ' is not a subspace.

5.2 Practical Problems

1. Determine the characteristic roots of the matrix space form solution:

The characteristic equation $A = |A - \lambda I| = 0$

$$A = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & -1 \\ 2 & -1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & -1 \\ 2 & -1 & 0 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 1 & 2 \\ 2 & -1 & -1 \\ 2 & -1 & -1 \end{bmatrix} = 0$$

$$\begin{bmatrix} -1 & 1 & 2 \\ 2 & -1 & -1 \\ 2 & -1 & -1 \end{bmatrix} = 0$$

$$\Rightarrow -1(\lambda^2 - 1) + 1(-\lambda + 2) + 2(-1 + 2\lambda) = 0$$

$$\Rightarrow -\lambda^3 + \lambda - \lambda + 2 - 2 + 4\lambda = 0$$

$$\Rightarrow -\lambda^3 + 4\lambda = 0$$

$$\Rightarrow \lambda(4 - \lambda^2) = 0$$

$$\lambda = 0, \lambda = -2, \lambda = 2$$

$$\lambda = -2, 0, 2$$

2. Verify Cayley-Hamilton theorem for the matrix $A = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & -1 & 1 \end{bmatrix}$

$$|A - \lambda I| = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & -1 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & -1 & 1 \end{bmatrix}$$

$$\Rightarrow (-1) \{(-1)^2 - 1\} - 2(0+3) + 1(0-3+3) = -1 - 6 + 1 = -6$$

$$= 1(\lambda^2 - 2\lambda) - \lambda(\lambda^2 - 2\lambda) - 6 - 3 + 3\lambda = \lambda^2 - 2\lambda - \lambda^3 + 2\lambda^2 - 6 - 3 + 3\lambda$$

$$= -\lambda^3 + 3\lambda^2 + \lambda - 9$$

The characteristic equation is given by $-\lambda^3 + 3\lambda^2 + \lambda - 9 = 0$
 By Cayley-Hamilton theorem, $-A^3 + 3A^2 + A - 9I = 0$. ①

NOW we verify equation ①

$$\begin{aligned} A^2 &= \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1+0+3 & 2+2-1 & 1-2+1 \\ 0+0-3 & 0+1+1 & 0-1-1 \\ 4+0+3 & 6-1-1 & 3+1+1 \end{bmatrix} = \begin{bmatrix} 4 & 3 & 0 \\ -3 & 2 & -2 \\ 6 & 4 & 5 \end{bmatrix} \\ A^3 &= \begin{bmatrix} 4 & 3 & 0 \\ -3 & 2 & -2 \\ 6 & 4 & 5 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 4-6+6 & 3+4+4 & 0-4+5 \\ 0-3-6 & 0+2-4 & 0-2-5 \\ 12+3+6 & 9-2+4 & 0+2+5 \end{bmatrix} = \begin{bmatrix} 4 & 11 & 1 \\ -9 & -2 & -7 \\ 21 & 11 & 7 \end{bmatrix} \\ \text{Now, } -A^3 + 3A^2 + A - 9I &= - \begin{bmatrix} 4 & 11 & 1 \\ -9 & -2 & -7 \\ 21 & 11 & 7 \end{bmatrix} + 3 \begin{bmatrix} 4 & 3 & 0 \\ -3 & 2 & -2 \\ 6 & 4 & 5 \end{bmatrix} + \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & -1 & 1 \end{bmatrix} - 9 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 4 & -11 & -1 \\ -9 & 2 & 7 \\ -21 & 11 & -2 \end{bmatrix} + \begin{bmatrix} 12 & 9 & 0 \\ -9 & 6 & -6 \\ 18 & 12 & 15 \end{bmatrix} + \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & -1 & 1 \end{bmatrix} - \begin{bmatrix} 9 & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 9 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = 0 \end{aligned}$$

Hence Cayley-Hamilton theorem is verified.

- (25) 6.3.1
 find the rank of the matrix A by reducing it to
 Echelon form where $A = \begin{bmatrix} 2 & -1 & 3 & 4 \\ 0 & 3 & 4 & 1 \\ 2 & 3 & 7 & 5 \\ 2 & 5 & 11 & 6 \end{bmatrix}$
solution:

$$A = \begin{bmatrix} 2 & -1 & 3 & 4 \\ 0 & 3 & 4 & 1 \\ 2 & 3 & 7 & 5 \\ 2 & 5 & 11 & 6 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_1 ; \quad R_4 \rightarrow R_4 - R_1$$

$$A = \begin{vmatrix} 2 & -1 & 3 & 4 \\ 0 & 3 & 4 & 1 \\ 0 & 4 & 4 & 1 \\ 6 & 6 & 8 & 2 \end{vmatrix}$$

$$R_4 \rightarrow R_4 - 2R_2$$

$$A = \begin{vmatrix} 2 & -1 & 3 & 4 \\ 0 & 3 & 4 & 1 \\ 0 & 4 & 4 & 1 \\ 0 & 0 & 0 & 0 \end{vmatrix}$$

$$R_3 \rightarrow R_3 - R_2$$

$$A = \begin{vmatrix} 2 & -1 & 3 & 4 \\ 0 & 3 & 4 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{vmatrix}$$

rank of A = The number of non-zero rows in echelon form = 3

6.3.2 Find the rank of the matrix A by reducing into normal form where $A = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 2 & 3 & 4 \\ 3 & 4 & 5 & 2 \end{bmatrix}$

solution:

$$R_2 \rightarrow R_2 - R_1, R_3 \rightarrow R_3 - 3R_1$$

$$A = \begin{vmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 0 & 0 \end{vmatrix}$$

$$C_3 \rightarrow C_3 - 2C_2, C_4 \rightarrow C_4 - 5C_2$$

$$A = \begin{vmatrix} 1 & 1 & 1 & -6 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{vmatrix}$$

$$C_3 \rightarrow C_3 + C_1, C_4 \rightarrow C_4 + 6C_1$$

$$A = \begin{vmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{vmatrix}$$

$$C_2 \rightarrow C_2 - C_1$$

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2} \begin{bmatrix} I_2 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

∴ Rant of given matrix - 2

$$= 0 =$$

(2) 6.3.3

Solve the system of equations

$$m + 2y + 3z = 0$$

$$2m + 3y + 4z = 0$$

$$7m + 13y + 19z = 0$$

solution:

The matrix equation of given system $AX = 0$ is given by

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 7 & 13 & 19 \end{bmatrix} \begin{bmatrix} m \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 7 & 13 & 19 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - 2R_1, R_3 \rightarrow R_3 - 7R_1$$

$$= \begin{bmatrix} 1 & 2 & 3 \\ 0 & -1 & -2 \\ 0 & -1 & -2 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_2$$

$$= \begin{bmatrix} 1 & 2 & 3 \\ 0 & -1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$$

The rank of coefficient matrix is 2

NOW the number of unknowns is 3

\therefore The given system possesses $3-2 = 1$ linearly independent solution.

linearly independent solution, we assign arbitrary values

The given system can be written as

$$m+2y+3z=0$$

$$-y-2z=0$$

$$\therefore y=-2z, m=-2z$$

put $z=c$, then $y=-2c, m=-c$

Hence $m=-c, y=-2c, z=c$ will constitute a solution for the given system of equations.

7.3.1

Obtain the matrix for the quadratic form $x^2+2y^2+3z^2+4xy+5yz+6zx$,

Solution:

Given equation $x^2+2y^2+3z^2+4xy+5yz+6zx$

it can be written as.

$$x^2+2xy+3xz+2yz+2y^2+\frac{5}{2}yz+3zx+\frac{5}{2}xy+3z^2$$

\therefore If A is the quadratic form, then

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 2 & \frac{5}{2} \\ 3 & \frac{5}{2} & 3 \end{bmatrix}$$

which is symmetric matrix of order 3.

7.4.2

Prove that the quadratic form

$$6x^2+4y^2+5z^2-8yz+2xz-4xy$$

in three variables is positive definite

Solution:-

Given quadratic form

$$6x^2 + 4xy^2 + 5y^2 - 4xy - 82yz + 20z^2$$

The Matrix A of given quadratic form is.

$$A = \begin{bmatrix} 6 & -2 & 10 \\ -2 & 49 & 41 \\ 10 & 41 & 51 \end{bmatrix}$$

The leading principle minors of A are

$$A_1 = 6$$

$$A_2 = \begin{vmatrix} 6 & -2 \\ -2 & 49 \end{vmatrix} = 294 - 4 = 290$$

$$A_3 = \begin{vmatrix} 6 & -2 & 10 \\ -2 & 49 & 41 \\ 10 & 41 & 51 \end{vmatrix} = 6(2599 - 881) \\ = 6(1718)$$

Since the leading principle minor = 11,308

positive we have the given quadratic form is positive definite.

(30) 7.4.3

Show that for the vectors $\alpha = (\alpha_1, \alpha_2)$ and $y = (y_1, y_2)$ form \mathbb{R}^2 the following defines an inner product on \mathbb{R}^2

$$(\alpha, y) = \alpha_1 y_1 - \alpha_2 y_1 - \alpha_1 y_2 + 2\alpha_2 y_2.$$

Solution:- We will show that all the positive of an inner product hold good.

1. Symmetry:-

$$\begin{aligned} (\alpha, y) &= y_1 \alpha_1 - y_2 \alpha_1 - y_1 \alpha_2 + 2\alpha_2 y_2 \\ &= \alpha_1 y_1 - \alpha_2 y_1 - \alpha_1 y_2 + 2\alpha_2 y_2 \\ &= (\alpha, y) \end{aligned}$$

Linearity

$$\begin{aligned} \text{Let } a, b \in \mathbb{R} \text{ then } a\mathbf{x} + b\mathbf{y} &= a(\mathbf{x}_1, \mathbf{x}_2) + b(\mathbf{y}_1, \mathbf{y}_2) \\ &= (a\mathbf{x}_1, a\mathbf{x}_2) + (b\mathbf{y}_1, b\mathbf{y}_2) \\ &= (a\mathbf{x}_1 + b\mathbf{y}_1, a\mathbf{x}_2 + b\mathbf{y}_2) \end{aligned}$$

$$\text{let } \mathbf{z} = (z_1, z_2) \in \mathbb{R}^2$$

$$\begin{aligned} (a\mathbf{x} + b\mathbf{y}, \mathbf{z}) &= (a\mathbf{x}_1 + b\mathbf{y}_1)z_1 - (a\mathbf{x}_2 + b\mathbf{y}_2)z_2 - (a\mathbf{x}_1 + b\mathbf{y}_1)z_2 + \\ &= a\mathbf{x}_1 z_1 - a\mathbf{x}_2 z_1 - a\mathbf{x}_1 z_2 + 2a\mathbf{x}_2 z_2 + b\mathbf{y}_1 z_1 - b\mathbf{y}_1 z_2 - b\mathbf{y}_2 z_1 \\ &\quad - b\mathbf{y}_1 z_2 + b\mathbf{y}_2 z_2 \\ &= a(\mathbf{x}_1 z_1 - \mathbf{x}_2 z_1 - \mathbf{x}_1 z_2 + 2\mathbf{x}_2 z_2) + b(\mathbf{y}_1 z_1 - \mathbf{y}_2 z_1 - \mathbf{y}_1 z_2 + 2\mathbf{y}_2 z_2) \\ &= a(\mathbf{x}, \mathbf{z}) + b(\mathbf{y}, \mathbf{z}) \end{aligned}$$

non-negativity

$$\begin{aligned} \text{we have } (\mathbf{x}, \mathbf{x}) &= \mathbf{x}_1 \mathbf{x}_1 - \mathbf{x}_2 \mathbf{x}_1 - \mathbf{x}_1 \mathbf{x}_2 + 2\mathbf{x}_2 \mathbf{x}_2 \\ &= \mathbf{x}_1^2 - 2\mathbf{x}_1 \mathbf{x}_2 + 2\mathbf{x}_2^2 \\ &= (\mathbf{x}_1 - \mathbf{x}_2)^2 + \mathbf{x}_2^2 \end{aligned}$$

non-negative real numbers which is the same of them.

$$(\mathbf{x}, \mathbf{x}) \geq 0$$

$$\begin{aligned} (\mathbf{x}, \mathbf{x}) = 0 &\Rightarrow (\mathbf{x}_1 - \mathbf{x}_2)^2 + \mathbf{x}_2^2 = 0 && \left| \begin{array}{l} \mathbf{x}_1 = 0, \mathbf{x}_2 = 0 \\ \therefore \text{the given product} \end{array} \right. \\ &\quad (\mathbf{x}_1 - \mathbf{x}_2)^2 = 0, \mathbf{x}_2^2 = 0 && \left| \begin{array}{l} \text{is an inner product} \\ \mathbf{x}_1 = \mathbf{x}_2 = 0, \mathbf{x}_2 = 0 \end{array} \right. \\ &\quad = 0 && \end{aligned}$$

8.3.2

Prove that the two vectors \mathbf{u} and \mathbf{v} in a real inner product space are orthogonal if and only if $\|\mathbf{u} + \mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$

Solution :-

$$\|\mathbf{u} + \mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 \Leftrightarrow (\mathbf{u} + \mathbf{v}, \mathbf{u} + \mathbf{v}) = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$$

$$\Rightarrow (\mathbf{u}, \mathbf{v}) + (\mathbf{u}, \mathbf{v}) + (\mathbf{v}, \mathbf{u}) + (\mathbf{v}, \mathbf{v}) = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$$

$$\Rightarrow \|\mathbf{u}\|^2 + (\mathbf{u}, \mathbf{v}) + (\mathbf{v}, \mathbf{u}) + \|\mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$$

$$\Rightarrow (\mathbf{u}, \mathbf{v}) + (\mathbf{u}, \mathbf{v}) = 0 \quad \because (\mathbf{u}, \mathbf{v}) \text{ is real.} (\bar{\mathbf{u}}, \mathbf{v} = (\mathbf{u}, \mathbf{v}))$$

Theorem: Basic Extension Theorem:-

1. Explain Basic & Dimension, Basic extension theorem.

Let $V(f)$ be a finite dimensional vector space.
 Let $S = \{a_1, a_2, \dots, a_r\}$ be a linearly independent subset of V . Then "S" itself is a basic of V if there exists a basic of V which contains S .
 (i.e) S can be extended to from a basic of V .

Proof:-

$V(f)$ is a finite dimensional $V(S)$
 $S = \{a_1, a_2, \dots, a_r\}$ is linearly independent. If S do not span V , then S itself is a basis. If do not span V , then there exists a vector a_{r+1} in V which can not be written as a linear combination of a_1, a_2, \dots, a_r .
 let $S_1 = \{a_1, a_2, \dots, a_r, a_{r+1}\}$. we observe that S_1 is linearly independent.

$$a_1a_2 + a_2a_2 + \dots + a_ra_r + a_{r+1} = 0 \rightarrow (1)$$

where $a_1, a_2, \dots, a_{r+1} \in V$.

(86)

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if $a_{r+1} \neq 0$ then there exists $a_{r+1}^{-1} \in F$ such that

$$a_{r+1} a_{r+1}^{-1} = a_{r+1}^{-1} a_{r+1} = 1$$

Now multiplying both sides of (1) by a_{r+1}^{-1} we

can see that a_{r+1} is a linear combination of a_1, a_2, \dots, a_r , which is false.

$$\text{Hence } a_{r+1} = 0$$

$$\therefore a_1 a_1 + a_2 a_2 + \dots + a_r a_r = 0$$

Since $\{a_1, a_2, \dots, a_r\}$ is linearly independent, a_1 ,

$$a_2 = a_3 = \dots = a_r = 0$$

Hence S_1 is linearly independent.

If S_1 spans V then S_1 is a basic of V and

contain S_1 .

If S_1 do not span V then there exists a vector a_{r+2} in V which can not be written as a linear combination of the elements of S_1 .

$$\text{let } S_2 = \{a_1, a_2, \dots, a_r, a_{r+1}, a_{r+2}\}.$$

Then as above we can show that S_2 is

linearly independent. If S_2 spans V then S_2 is a basic of V and S_2 contains S_1 . If $L(S_2) \neq V$

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then we repeat the above procedure. This procedure continues infinitely then we get an infinite number of linearly independent vectors in a finite dimensional vector space which is false. [Because in a finite dimensional vector space the number of spanning vectors is finite. and hence the number linearly independent vectors is also finite]. Hence at some stage we get a set S_k which is linearly independent and spanned. Hence S_1 is the basis of V and also S_k contains S_1 .

NOTE:-

If $V(f)$ is a finite dimensional vector space then any every basis of V is finite.

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4. If w_1 & w_2 are subspaces of a finite dimensional vector space $V(f)$ then.

$$\dim(w_1 + w_2) = \dim(w_1) + \dim(w_2) - \dim(w_1 \cap w_2)$$

Proof:

$w_1, w_2, w_1 + w_2, w_1 \cap w_2$ are subspaces of the finite dimensional vector space $V(f)$. Hence $w_1, w_2, w_1 + w_2, w_1 \cap w_2$ are also finite dimensional subspaces. Let $S = \{r_1, r_2, \dots, r_k\}$ be a basis of $w_1 \cap w_2$ so that $\dim(w_1 \cap w_2) = k$.

Now $w_1 \cap w_2 \subset w_1$, hence S is linearly independent in w_1 . Hence by the basis Extension theorem, S can be extended to form a basis of w_1 .

Let $S_1 = \{\alpha_1, \alpha_2, \alpha_3, \dots, \alpha_n, \gamma_1, \gamma_2, \dots, \gamma_k\}$ be a basis of w_1 .

$$\therefore \dim w_1 = n+k$$

Similarly by the same argument, S can be extended to form a basis of w_2 .

Let $S_2 = \{\beta_1, \beta_2, \dots, \beta_m, \vartheta_1, \vartheta_2, \dots, \vartheta_k\}$ be a basis of w_2 .

$$\text{Hence } \dim w_2 = m+k$$

$$\text{Now } \dim w_1 + \dim w_2 - \dim(w_1 \cap w_2)$$

$$= n+k+m+k-k$$

$$= n+m+k.$$

We shall prove that $\dim(w_1 + w_2) = n+m+k$.

for this we show that there exists a basis of $w_1 + w_2$ which contains $n+m+k$ elements.

let $S' = \{\alpha_1, \alpha_2, \dots, \alpha_n, \beta_1, \beta_2, \dots, \beta_m, \gamma_1, \gamma_2, \dots, \gamma_k\}$

We shall prove that S' is a basis of $w_1 + w_2$.

S' is linearly independent:-

$$\text{Let } a_1\alpha_1 + a_2\alpha_2 + \dots + a_n\alpha_n + b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m + c_1\gamma_1 + c_2\gamma_2 + \dots + c_k\gamma_k = 0 \quad \rightarrow ①$$

for some $a_1^S, a_2^S, \dots, a_n^S, b_1^S, b_2^S, \dots, b_m^S, c_1^S, c_2^S, \dots, c_k^S \in F$

$$\text{Now } b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m$$

$$= -(a_1\alpha_1 + a_2\alpha_2 + \dots + a_n\alpha_n + c_1\gamma_1 + c_2\gamma_2 + \dots + c_k\gamma_k)$$

$$a_1\alpha_1 + a_2\alpha_2 + \dots + a_n\alpha_n + c_1\gamma_1 + c_2\gamma_2 + \dots + c_k\gamma_k \in w_1$$

(Because it is a lc of the elements of w_1)

$$\therefore b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m \in w_1$$

$$\text{but } b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m$$

$$= b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m + 0\cdot\gamma_1 + 0\cdot\gamma_2 + \dots + 0\cdot\gamma_k \in w_2$$

$$\text{Hence } b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m \in w_1 \cap w_2$$

Since $\{\gamma_1, \gamma_2, \dots, \gamma_k\}$ is a basis of $w_1 \cap w_2$ we can

(Signature) P. Anitha

write $b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m = d_1\gamma_1 + d_2\gamma_2 + \dots + d_k\gamma_k$ for some $d_i^S \in F$

$$\Rightarrow b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m - d_1\gamma_1 - d_2\gamma_2 - \dots - d_k\gamma_k = 0 \text{ for } \gamma_i \in S$$

Some $d_i^S \in F$

But $\{\beta_1, \beta_2, \dots, \beta_m, \gamma_1, \gamma_2, \dots, \gamma_k\}$ is a basis of w_2 & hence linearly independent.

$$\therefore b_1 = b_2 = \dots = b_m = d_1 = d_2 = \dots = d_k = 0$$

Hence by (1)

$$a\alpha_1 + a_2\alpha_2 + \dots + a_n\alpha_n + c_1\gamma_1 + c_2\gamma_2 + \dots + c_k\gamma_k = 0$$

But $\{\alpha_1, \alpha_2, \dots, \alpha_n, \gamma_1, \gamma_2, \dots, \gamma_k\}$ is a basis of w_1 & hence linearly independent.

$$\therefore a_1 = a_2 = \dots = a_n = c_1 = c_2 = \dots = c_k = 0$$

$\therefore S'$ linearly independent.

S' span $w_1 + w_2$

let $\gamma \in w_1 + w_2$

we can write $\gamma = \alpha + \beta$ for some $\alpha \in w_1$ & $\beta \in w_2$

$\alpha \in w_1$ & S_1 is a basis of w_1 , hence we can write

$$\alpha = \sum_{i=1}^k a_i \alpha_i + \sum_{i=1}^k b_i \gamma_i \text{ for some } a_i^S, b_i^S \in F$$

$\beta \in w_2$ & S_2 is a basis of w_2 then we can write

$$\beta = \sum_{i=1}^m d_i \beta_i + \sum_{i=1}^k e_i \gamma_i \text{ for some } d_i^S, e_i^S \in F$$

write $b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m = d_1\gamma_1 + d_2\gamma_2 + \dots + d_k\gamma_k$ for some $d_i^S \in F$

$\Rightarrow b_1\beta_1 + b_2\beta_2 + \dots + b_m\beta_m - d_1\gamma_1 - d_2\gamma_2 - \dots - d_k\gamma_k = 0$ for some $d_i^S \in F$

But $\{\beta_1, \beta_2, \dots, \beta_m, \gamma_1, \gamma_2, \dots, \gamma_k\}$ is a basis of w_2 & hence linearly independent.

$$\therefore b_1 = b_2 = \dots = b_m = d_1 = d_2 = \dots = d_k = 0$$

Hence by (1)

$$a_1\alpha_1 + a_2\alpha_2 + \dots + a_n\alpha_n + c_1\gamma_1 + c_2\gamma_2 + \dots + c_k\gamma_k = 0$$

But $\{\alpha_1, \alpha_2, \dots, \alpha_n, \gamma_1, \gamma_2, \dots, \gamma_k\}$ is a basis of w_1 & hence linearly independent.

$$\therefore a_1 = a_2 = \dots = a_n = c_1 = c_2 = \dots = c_k = 0$$

$\therefore S'$ linearly independent.

S' span $w_1 + w_2$

let $\gamma \in w_1 + w_2$

we can write $\gamma = \alpha + \beta$ for some $\alpha \in w_1$, $\beta \in w_2$

$\alpha \in w_1$, & S_1 is a basis of w_1 , hence we can write.

$$\alpha = \sum_{i=1}^k a_i \alpha_i + \sum_{i=1}^k b_i \gamma_i \text{ for some } a_i^S, b_i^S \in F$$

$\beta \in w_2$ & S_2 is a basis of w_2 then we can write.

$$\beta = \sum_{i=1}^M d_i \beta_i + \sum_{i=1}^K e_i \gamma_i \text{ for some } d_i^S, e_i^S \in F$$

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Hence $\tau = \alpha + \beta = \sum_{i=1}^n \alpha_i e_i + \sum_{i=1}^m \alpha_i B_i + \sum_{i=1}^k (\beta_i + e_i) \gamma_i$

which is a linear combination of the elements of S'

of S' , i.e., sum of ratios of subspaces $\text{span}(B_i)$ and $\text{span}(e_i)$

Hence S' Span $w_1 + w_2$

and S' is a basis of $w_1 + w_2$ since w_1, w_2 are linearly independent

i.e., $\dim(w_1 + w_2) = n + m + k$ since w_1, w_2 are linearly independent

and $\dim A = \dim w_1 + \dim w_2 - \dim(w_1 \cap w_2)$ since w_1, w_2 are linearly independent

$\dim(w_1 \cap w_2) = 0$ as $w_1 \cap w_2 = \{0\}$ since w_1, w_2 are linearly independent

and $\dim A = n + m + k - (n + m) = k$ since w_1, w_2 are linearly independent

and $w_1 + w_2$ is a basis of A and w_1, w_2 are linearly independent

and w_1, w_2 are linearly independent in A because w_1, w_2 are linearly independent in S'

and w_1, w_2 are linearly independent in S' because w_1, w_2 are linearly independent in S

and w_1, w_2 are linearly independent in S because w_1, w_2 are linearly independent in S'

and w_1, w_2 are linearly independent in S' because w_1, w_2 are linearly independent in S

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and w_1, w_2 are linearly independent in S' because w_1, w_2 are linearly independent in S

and w_1, w_2 are linearly independent in S because w_1, w_2 are linearly independent in S'

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5. Find the characteristic roots & the corresponding characteristic vectors of the matrix $A = \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix}$

Aim:- To find the characteristic roots & the corresponding characteristic vector of the given matrix.

Formula:-

(i) If A is square matrix of order n & I is the $n \times n$ unit matrix then $|A - \lambda I| = 0$ where λ is a scalar, is called the characteristic equation of A & the roots of the characteristic eqn are the characteristic roots of A .

(ii) Let A be a square matrix then a nonzero vector x is called a characteristic vector of A , if there exists a scalar λ such that $Ax = \lambda x$.

Procedure:-

Given that $A = \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix}$

Then the characteristic eqn of A is $A - \lambda I = 0$

$$\Rightarrow \begin{vmatrix} 8-\lambda & -6 & 2 \\ -6 & 7-\lambda & -4 \\ 2 & -4 & 3-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (8-\lambda) [(7-\lambda)(3-\lambda) - 16] + 6 [-6(3-\lambda) + 8] + 2 [24 - 2(7-\lambda)] = 0$$

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$$\Rightarrow (8-\lambda) [\lambda^2 - 10\lambda + 5] + 6 [6\lambda - 10] + 2 [2\lambda + 10]$$

$$= 8\lambda^2 - 80\lambda + 40 - \lambda^3 + 10\lambda^2 - 5\lambda + 36\lambda - 60 + 4\lambda + 20 = 0.$$

$$= -\lambda^3 + 18\lambda^2 - 45\lambda = 0$$

$$= -\lambda^2(18\lambda - 45) = 0$$

$$= \lambda(\lambda^2 - 18\lambda + 45) = 0$$

$$\therefore \lambda(\lambda - 3)(\lambda - 15) = 0$$

$$\lambda = 0, 3, 15$$

1. Let $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ be a characteristic vector corresponding

to $\lambda = 0$

Then $Ax = \lambda x \Rightarrow Ax = 0x = 0$

$$= \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \xrightarrow{R_1 \cdot 3} \begin{bmatrix} 2 & -4 & 3 \\ -6 & 7 & -4 \\ 8 & -6 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\xrightarrow{R_2 + 3R_1} \begin{bmatrix} 2 & -4 & 3 \\ 0 & -5 & 5 \\ 0 & 10 & -10 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$R_3 - 4R_1$$

$$\xrightarrow{R_2 \times -1} \begin{bmatrix} 2 & -4 & 3 \\ 0 & 1 & -1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$\xrightarrow{R_3 \times -10}$$

(Signature : S. Kotuswara Rao)

$$\xrightarrow{R_3+R_2} \begin{bmatrix} 2 & -4 & 3 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$\therefore 2x_1 - 4x_2 + 3x_3 = 0$ & $-x_2 + x_3 = 0$ $\Rightarrow x_2 = x_3$

The above equation are $2x_1 - 4x_2 + 3x_3 = 0$ & $-x_2 + x_3 = 0$

$$\text{if } x_2 = k \text{ then } x_3 = k$$

$$\therefore 2x_1 - 4k + 3k = 0 \Rightarrow 2x_1 - k = 0 \Rightarrow x_1 = \frac{k}{2}$$

$$\therefore x = \begin{bmatrix} k/2 \\ k \\ k \end{bmatrix} = k \begin{bmatrix} 1/2 \\ 1 \\ 1 \end{bmatrix}$$

Hence the characteristic vectors corresponding to

$$\lambda = 0 \text{ are } k \begin{bmatrix} 1/2 \\ 1 \\ 1 \end{bmatrix}$$

where k is a non-zero scalar.

2) Let $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ be a characteristic vector corresponding to $\lambda = 3$ then $Ax = 3x$

$$\Rightarrow (A - 3I)x = 0$$

$$\begin{bmatrix} 5 & -6 & 2 \\ -6 & 4 & -4 \\ 2 & -4 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \xrightarrow{R_1 \times 3} \begin{bmatrix} 2 & -4 & 0 \\ -6 & 4 & -4 \\ 5 & -6 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$\xrightarrow{R_1 \times 2} \begin{bmatrix} 1 & -2 & 0 \\ -3 & 2 & -2 \\ 5 & -6 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \xrightarrow{\substack{R_2 + 3R_1 \\ R_3 - 5R_1}} \begin{bmatrix} 1 & -2 & 0 \\ 0 & -4 & -2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$\xrightarrow{R_1 \times 3} \begin{bmatrix} 1 & -2 & 0 \\ 0 & -4 & -2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \xrightarrow{R_2 \times -\frac{1}{4}} \begin{bmatrix} 1 & -2 & 0 \\ 0 & 1 & 0.5 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

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$$\xrightarrow{R_1 \times -Y_2} \begin{bmatrix} 1 & -2 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

Hence the equations are $x_1 - 2x_2 = 0$.

$$x_2 + x_3 = 0$$

Hence the characteristic vectors corresponding to $\lambda = 3$

are $K \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$ where K is a non-zero scalar.

Let $\lambda = 15$ & $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ be a characteristic vector corresponding to $\lambda = 15$.

$$Ax = 15x$$

$$\Rightarrow [A - 15I]x = 0$$

$$\begin{bmatrix} -7 & -6 & 2 \\ -6 & -8 & -4 \\ 2 & -4 & -12 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \xrightarrow{R_1 \times 3}$$

$$\begin{bmatrix} 2 & -4 & -12 \\ -6 & -8 & -4 \\ -7 & -6 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \xrightarrow{\begin{array}{l} R_1 \times Y_2 \\ R_2 \times Y_2 \end{array}} \begin{bmatrix} 1 & -2 & -6 \\ -3 & -4 & -2 \\ -7 & -1 & -6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$\xrightarrow{R_2 + 3R_1} \begin{bmatrix} 1 & -2 & -6 \\ 0 & -10 & -20 \\ 0 & -20 & -40 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \xrightarrow{R_2 \times -1/10} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$R_3 \times -Y_2$$

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$$\begin{bmatrix} 1 & -2 & -6 \\ 0 & 1 & 2 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \xrightarrow{R_3 + R_2} \begin{bmatrix} 1 & -2 & -6 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

Hence the equations are $x_1 - 2x_2 - 6x_3 = 0$

$$x_2 + 2x_3 = 0$$

$$\text{if } x_3 = k \text{ then } x_2 = -2k$$

$$x_1 = -4k + 6k = 2k$$

Hence the characteristic vectors corresponding to $\lambda=15$ are $k \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$ where k is a non-zero scalar.

Conclusion:-

The characteristic vectors of A are $0, 3, 15$.

1. The characteristic vectors corresponding to $\lambda=0$ are $k \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$ where k is a non zero scalar.

2. The characteristic vectors corresponding to $\lambda=3$ are $k \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$ where k is a nonzero scalar.

3. The characteristic vectors corresponding to $\lambda=15$ are $k \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$ where k is a non-zero scalar.

S. Koteswara Rao

Name: L. KRISHNARAO

Explain Bessel's Inequality

Date 22-02-2022

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State and prove Bessel's inequality in an inner product space.

Statement:- If $S = \{\alpha_1, \alpha_2, \dots, \alpha_n\}$ is an orthonormal subset in an inner product space $V(f)$ and $\beta \in V$ then

$$\left| \sum_{i=1}^n |\langle \beta, \alpha_i \rangle|^2 \right| \leq \|\beta\|^2$$

Proof:- $S = \{\alpha_1, \alpha_2, \dots, \alpha_n\}$ is an orthonormal set.

$$\Rightarrow \langle \alpha_i, \alpha_j \rangle = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$$

Consider, the vector $\gamma \in V$ such that $\gamma = \beta - \sum_{i=1}^n \langle \beta, \alpha_i \rangle \alpha_i$

$$\langle \gamma, \gamma \rangle = \langle \beta - \sum_{i=1}^n \langle \beta, \alpha_i \rangle \alpha_i, \beta \rangle = \sum_{i=1}^n \langle \beta, \alpha_i \rangle \alpha_i$$

$$= (\beta, \beta) = \langle \beta, \sum_{i=1}^n \langle \beta, \alpha_i \rangle \alpha_i \rangle - \langle \sum_{i=1}^n \langle \beta, \alpha_i \rangle \alpha_i, \beta \rangle$$

$$+ \langle \sum_{i=1}^n \langle \beta, \alpha_i \rangle \alpha_i, \sum_{i=1}^n \langle \beta, \alpha_i \rangle \alpha_i \rangle$$

$$= \|\beta\|^2 - \sum_{i=1}^n \langle \beta, \alpha_i \rangle \langle \beta, \alpha_i \rangle - \sum_{i=1}^n \langle \beta, \alpha_i \rangle \langle \alpha_i, \beta \rangle$$

$$- \sum_{i=1}^n \langle \beta, \alpha_i \rangle \sum_{i=1}^n \langle \beta, \alpha_i \rangle \langle \alpha_i, \alpha_i \rangle$$

$$= \|\beta\|^2 - \sum_{i=1}^n \langle \beta, \alpha_i \rangle \langle \beta, \alpha_i \rangle - \sum_{i=1}^n \langle \beta, \alpha_i \rangle \langle \beta, \alpha_i \rangle$$

$$+ \sum_{i=1}^n (\beta, \alpha_i) \langle \beta, \alpha_i \rangle \langle \alpha_i, \alpha_i \rangle$$

$$= \|\beta\|^2 - \sum_{i=1}^n \langle \beta, \alpha_i \rangle \langle \beta, \alpha_i \rangle$$

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$$\|\beta\|^2 = \sum_{i=1}^n \|z_i\|^2$$

$$\langle \gamma, \gamma \rangle = \|\beta\|^2 = \sum_{i=1}^n |\langle \beta, \alpha_i \rangle|^2$$

we know that $\|\beta\| \geq 0$

$$\Rightarrow \|\gamma\| \geq 0$$

$\Rightarrow \langle \gamma, \gamma \rangle \geq 0$ satisfying non-negativity condition

$$\Rightarrow \|\beta\|^2 = \sum_{i=1}^n |\langle \beta, \alpha_i \rangle|^2$$

$$\Rightarrow \sum_{i=1}^n |\langle \beta, \alpha_i \rangle|^2 \leq \|\beta\|^2$$

LMax

9. State and Prove Stoke's Theorem

Statement: let "S" be a closed surface enclosed by a curve "C". If "f" continuously differentiable vector point function, then

$$\int_S \text{curl } f \cdot N \, dS = \oint_C f \cdot dr$$

Proof:- Let "S" be a closed surface enclosed by curve "C"

$$F = F_1 i + F_2 j + F_3 k$$

$$\text{Consider } \nabla \times F_1 i = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & 0 & 0 \end{vmatrix}$$

$$= i(0-0) - j(0 - \frac{\partial F_1}{\partial z}) + k(0 - \frac{\partial F_1}{\partial y})$$

$$= -\frac{\partial F_1}{\partial z} j \cdot N \, dS + \frac{\partial F_1}{\partial y} k \cdot N \, dS \quad (1)$$

Let $z = f(x, y)$ be the equation of S

for any point on S, $r = xi + yj + zk$

$$\Rightarrow \frac{dr}{dy} = j + \frac{\partial z}{\partial y} \cdot k$$

Let $z = f(x, y)$ be the equation of S

(Signature: P. Anil Kumar)

Since $\frac{dr}{dy}$ is a tangent vector to S and N is normal to S.

$$\frac{dr}{dy} \cdot N = 0$$

$$(j + \frac{dz}{dy} k) \cdot N = 0$$

$$(j + \frac{dz}{dy} k) N = 0$$

$$j \cdot N + \frac{dz}{dy} (k \cdot N) = 0$$

$$j \cdot N = -\frac{dz}{dy} (k \cdot N)$$

Substituting this value in Eqn ①

$$\begin{aligned} (\nabla \times f_i) N ds &= \frac{df_i}{dz} \left[-\frac{dz}{dy} (k \cdot N) \right] \cdot ds - \frac{df_i}{dy} k \cdot N ds \\ &= - \left[\frac{df_i}{dz} \cdot \frac{dz}{dy} + \frac{df_i}{dy} \right] k \cdot N ds \\ &= - \frac{\delta f_i}{dy} k \cdot N ds \end{aligned}$$

Let R be the projection of S in xy plane

$$ds = \frac{dx \cdot dy}{N \cdot k}$$

$$N \cdot k \ ds = \delta x \cdot \delta y$$

$$\begin{aligned} \text{Now, } S(\nabla \times f_i) N ds &= - \frac{\delta f_i}{dy} k \cdot N ds \\ &= \iint_S - \frac{df_i}{dy} dx \cdot dy \\ &= \oint_C f_i dx \quad (\text{By greens theorem}) \end{aligned}$$

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$$\therefore \int_S (\nabla \times f_i i) \cdot N dS = \oint_C f_i \cdot dx \rightarrow \textcircled{A}$$

$$\text{Similarly } \int_S (\nabla \times f_2 j) \cdot N dS = \oint_C f_2 \cdot dy \rightarrow \textcircled{B}$$

$$\int_S (\nabla \times f_3 k) \cdot N dS = \oint_C f_3 \cdot dz \rightarrow \textcircled{C}$$

 $\textcircled{A} + \textcircled{B} + \textcircled{C}$

$$\int_S \nabla \times (f_1 i + f_2 j + f_3 k) \cdot N dS = \oint_C f_1 dx + f_2 dy + f_3 dz$$

$$\Rightarrow \int_S (\nabla \times f) \cdot N dS = \oint_C f \cdot dr$$

$$\boxed{\int_S \text{curl } f = \oint_C f \cdot dr}$$

This is called "Stoke's theorem"

Signature: P. Anil Kumar

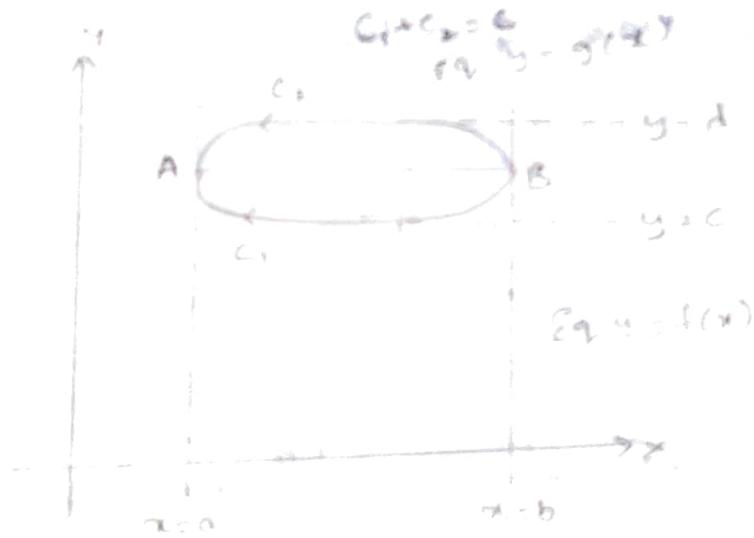
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10. State and prove Green's Theorem

Statement :- If p and q are two continuously differentiable scalar point functions, then

$$\oint_C p dx + q dy = \iint_S \left(\frac{\partial q}{\partial x} - \frac{\partial p}{\partial y} \right) dx dy$$

Proof :- Let p and q be two continuously differentiable scalar point function and "S" be closed surface enclosed by a curve "C".



Let C_1 be the lower point of C and C_2 be the upper point of C .

Let $y=f(x)$ be the equation of C_1 and $y=g(x)$ be the equation of C_2 .

Suppose "S" lies b/w $x=a, y=c, x=b, y=0$

$$\text{Now } \iint_S \frac{\partial p}{\partial y} dx dy = \int_{x=a}^{x=b} \left[\int_{y=f(x)}^{y=g(x)} \frac{\partial p}{\partial y} dy \right] dx$$

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$$\begin{aligned}
 &= \int_{x=a}^{x=b} [p(x, y)]_{y=f(x)}^{y=g(x)} dx \\
 &= \int_{x=a}^{x=b} [p(x), g(x) - p(x), f(x)] dx \\
 &= \int_{x=a}^{x=b} p(x), g(x) dx - \int_{x=a}^{x=b} p(x), f(x) dx \\
 &= - \left[\int_{C_1} + \int_{C_2} p(x, y) dx \right] \\
 &= - \oint_C p dx \\
 \therefore \quad &\iint_S \frac{dp}{dy} dx dy = \oint_C p \cdot dx \\
 \Rightarrow \quad &\oint_C p dx = \iint_S \frac{dp}{dy} dx \cdot dy \quad \text{--- (A)} \\
 \text{By } \quad &\oint_C Q dy = \iint_S \frac{dq}{dx} dx \cdot dy \quad \text{--- (B)}
 \end{aligned}$$

(A) + (B)

$$\begin{aligned}
 \oint_C p dx + Q dy &= - \iint_S \frac{dp}{dy} dx \cdot dy + \iint_S \frac{dq}{dx} dx \cdot dy \\
 \oint_C p dx + Q dy &= \iint_S \left(\frac{dq}{dx} + \frac{dp}{dy} \right) dx \cdot dy
 \end{aligned}$$

(Signature: T. Mahimkumar)

$$\oint_C P dx + Q dy = \iint_S \left(\frac{\partial Q}{\partial x} + \frac{\partial P}{\partial y} \right) dx dy$$

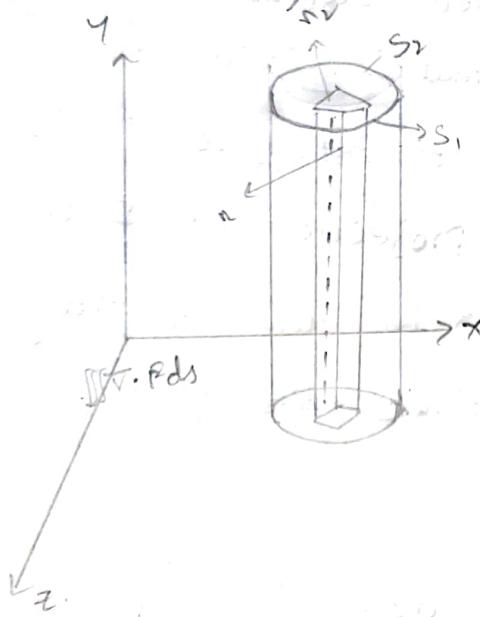
∴ This is called green's theorem.

T. Mohan Kudri

State and Prove Gauss Divergence Theorem.

Statement:- If S is a closed Surface enclosed a volume v and f is a continuously differentiable vector point function then $\int \text{div. } f dv = \int_S F \cdot N ds$ where N is a unit outward drawn Normal at any point on S.

Cartesian form:-



Let $F = F_1 i + F_2 j + F_3 k$. Let the unit normal vector N, drawn outward make angles α, β, γ with positive direction of the coordinate axes then

$$N = \cos \alpha i + \cos \beta j + \cos \gamma k$$

$$F \cdot N = F_1 \cos \alpha + F_2 \cos \beta + F_3 \cos \gamma \text{ and}$$

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$$\operatorname{div} \cdot F = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

Divergence theorem in Cartesian form can be written,

$$\text{as } \iiint_V \left[\frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \right] dx dy dz = \iint_S (F_1 \cos \alpha + F_2 \cos \beta + F_3 \cos \gamma) dS$$

$$= \iint_S (f_1 dy dz + f_2 dz dx + f_3 dx dy)$$

Proof:-

let S be a closed surface. Now choose the coordinate axes such that any line drawn parallel to the axes cuts S in atmost two points.

Let R be the projection of S on xy -plane.
 $z = f(x, y)$ and $z = g(x, y)$ be the equations of S_1 and S_2 which are respectively the lower and upper parts of S .

$$\text{Now } \int_V \frac{\partial f_3}{\partial z} dv = \iiint_V \frac{\partial f_3}{\partial z} dx dy dz = \iint_R f_3(x, y, z) \Big|_{z=f(x,y)}^{z=g(x,y)} dx dy$$

$$= \iint_R [F_3(x, y, g) - f_3(x, y, f)] dx dy$$

$$= \iint_R [R_3(x, y, g)] dx dy - \iint_R [F_3(x, y, f)] dx dy - (1)$$

for the upper part S_2 of S , $dxdy = dS \cdot \cos\theta = N \cdot k dS$

$$\iint_R f_3(x, y, z) dx dy = \int_{S_1} f_3 \cdot N \cdot k dS$$

for the lower part S_1 of S , $dxdy = -dS \cdot \cos\theta = -N \cdot k dS$

$$\iint_R f_3(x, y, z) dx dy = - \int_{S_2} F_3 \cdot N \cdot k dS$$

Hence from (1) $\int_V \frac{\partial F_3}{\partial z} dv = \int_{S_2} F_3 N \cdot k dS = \int_S F_3 N \cdot k dS$

By projecting 'S' on the other coordinate planes we get

$$\int_V \frac{\partial F_2}{\partial y} dv = \int_S F_2 N \cdot j dS \quad (2)$$

and $\int_V \frac{\partial F_1}{\partial x} dv = \int_S F_1 N \cdot i dS \quad (3)$

Adding the eqns (1), (2) and (3)

$$\int_V \left[\frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \right] dv = \int_S (F_1 i + F_2 j + F_3 k) \cdot N dS$$

\therefore hence $\int_V \text{div. } F dv = \int_S F \cdot N dS$

\therefore This is called Gauss Divergence theorem.

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- 5) Paidi, Leesa

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8) Durnu, Ramya Ashwini

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